# Total mean curvature surfaces in the product space $\mathbb{S}^{n} \times \mathbb{R}$ and applications. <br> Sylvia Ferreira <br> UFRPE 

sylvia.ferreira@ufrpe.br

## Introduction

An interesting line of research is to study which submanifolds are critical points of certain functional. In this scenario, we can highlight the work from [1, 2], being the last one concerning about the the total mean curvature functional, for a submanifold $\sigma^{m}$ in the Euclidean space, $\mathcal{H}$ given by

$$
\begin{equation*}
\mathcal{H}(\Sigma)=\int_{\Sigma} H^{m} d \Sigma \tag{1}
\end{equation*}
$$

and $\boldsymbol{H}$ is the mean curvature function of the submanifold. Our main result is inspired by the functional (1) and our aim is to study the $\mathcal{H}$-surfaces in the product space $\mathbb{S}^{n} \times \mathbb{R}$, i.e, surfaces which are critical points of the $\mathcal{H}$ functional in order to obtain an integral inequality relating the total umbilicity tensor $|\phi|$ and the Euler- Lagrange characteristic of the surface. As a consequence we characterizes those in what the equality holds. The results presented here are a part of [6].

## 1 Set up

Let $\Sigma^{m}$ be a submanifold isometrically immersed in the product space $\mathbb{S}^{n} \times \mathbb{R}$. We denote by $\partial_{t}$ the parallel and unitary vector field associated to this product and the second fundamental form of the imersion by $\sigma$, with $A_{\xi}$ being the Weingarten Operator in the normal direction $\boldsymbol{\xi}$. Since $\partial_{t} \in$ $\mathfrak{X}\left(\mathbb{S}^{n} \times \mathbb{R}\right)$, it can be decomposed along $\Sigma^{m}$ as $\partial_{t}=T+N$, where $T:=\partial_{t}^{\top}$ and $N:=\partial_{t}^{\perp}$ denote, respectively, the tangent and normal part of the vector field $\partial_{t}$ on the tangent and normal bundle of the submanifold $\Sigma^{m}$ in $\mathbb{S}^{n} \times \mathbb{R}$. Let us denote by $\boldsymbol{h}$ the mean curvature vector field of $\boldsymbol{\Sigma}^{m}$ in $\mathbb{S}^{n} \times \mathbb{R}$, and by $\boldsymbol{H}$ its norm, i.e, $\langle\boldsymbol{h}, \boldsymbol{h}\rangle=\boldsymbol{H}^{2}$.
Proposition 1. Let $\boldsymbol{x}: \Sigma^{m} \rightarrow \mathbb{S}^{n} \times \mathbb{R}$ be an isometrically immersed closed submanifold. Then $\boldsymbol{x}$ is a stationary point of $\mathcal{H}$ if and only if

$$
\begin{align*}
& H^{m-2}\left\{\Delta^{\perp} h+\left(\left(m-|T|^{2}\right)-m H^{2}\right) h-m\langle N, h\rangle N\right\} \\
& +\left(\sum_{\alpha, \beta} H^{\alpha} \operatorname{tr}\left(A_{\alpha} A_{\beta}\right) e_{\beta}\right)=0, \text { for } m>2 \text { and } \tag{2}
\end{align*}
$$

$$
\begin{align*}
& \Delta^{\perp} h+\left(2-|T|^{2}-2 H^{2}\right) h-2\langle N, h\rangle N \\
& +\sum_{\alpha, \beta} H^{\alpha} \operatorname{tr}\left(A_{\alpha} A_{\beta}\right) e_{\beta}=0 \tag{3}
\end{align*}
$$

in the case where $m=2$, where $m+1 \leq \alpha, \beta \leq n+1$.

## Main Result

Before proving our main result, we need the following proposition.
Proposition 2. Let $\Sigma^{2}$ be an $\mathcal{H}$-surface in the product space $\mathbb{S}^{n} \times \mathbb{R}$. Then, we have

$$
\begin{align*}
& \int_{\Sigma}\left(\left|\nabla^{\perp} \sigma\right|^{2}+2 \sum_{\alpha} \operatorname{tr}\left(A_{\alpha} \circ \operatorname{Hess} H^{\alpha}\right)\right) d \Sigma  \tag{4}\\
& \geq \int_{\Sigma}\left(2\langle N, h\rangle^{2}-\left(2-|T|^{2}+|\phi|^{2}\right) H^{2}\right) d \Sigma
\end{align*}
$$

Theorem 1. Let $\Sigma^{2}$ be a compact $\mathcal{H}$-surface in the product space $\mathbb{S}^{n} \times \mathbb{R}$. Then

$$
\begin{align*}
& \int_{\Sigma}|\phi|^{2}\left(1-5|T|^{2}-\frac{3}{2}|\phi|^{2}\right) d \Sigma  \tag{5}\\
& -\int_{\Sigma}\left\{2\left(\left|\phi_{h}\right|+1\right)|T|^{2}+2\right\} d \Sigma \leq 4 \pi \chi(\Sigma)
\end{align*}
$$

In particular, the equality holds if and only if $\Sigma^{2}$ is isometric to either
(i) a slice $\mathbb{S}^{2} \times\left\{t_{0}\right\}$, or
(ii) a totally geodesic 2 -sphere or a Clifford torus in $\mathbb{S}^{3} \times\left\{t_{0}\right\}$, (iii) or a Veronese surface in $\mathbb{S}^{4} \times\left\{t_{0}\right\}$, for some $t_{0} \in \mathbb{R}$.

Proof. With a straighforward computation the [3, Proposition 1] can be written as follow
$\frac{1}{2} \Delta|\sigma|^{2} \geq\left|\nabla^{\perp} \sigma\right|^{2}+2 \sum_{\alpha} \operatorname{tr}\left(A_{\alpha} \circ\right.$ Hess $\left.H^{\alpha}\right)+2\left|\phi_{N}\right|^{2}$
$-2\left|\phi_{h}\right||T|^{2}+\left(2-5|T|^{2}+2 H^{2}-\frac{3}{2}|\phi|^{2}\right)|\phi|^{2}$.
Taking the integrals and using the divergence theorem, it follows from Proposition 2 that,
$0 \geq \int_{\Sigma}\left\{2\left(\left|\phi_{N}\right|^{2}+\langle N, h\rangle^{2}\right)+\left(|T|^{2}+|\phi|^{2}\right) H^{2}\right\} d \Sigma$
$+\int_{\Sigma}\left\{\left(2-5|T|^{2}-\frac{3}{2}|\phi|^{2}\right)-2 H^{2}-2\left|\phi_{h}\right||T|^{2}\right\} d \Sigma$.
Hence
$\int_{\Sigma}\left\{\left(2-5|T|^{2}-\frac{3}{2}|\phi|^{2}\right)|\phi|^{2}-2 H^{2}-2\left|\phi_{h}\right||T|^{2}\right\} d \Sigma$
$\leq 0$.
Then, the Gauss-Bonnet theorem implies

$$
\begin{align*}
& \int_{\Sigma}\left\{\left(1-5|T|^{2}-\frac{3}{2}|\phi|^{2}\right)|\phi|^{2}\right\} d \Sigma \\
& -\int_{\Sigma}\left\{2\left(\left|\phi_{h}\right|+1\right)|T|^{2}+2\right\} d \Sigma \leq 4 \pi \chi(\Sigma) \tag{6}
\end{align*}
$$

Finaly, if the equality holds in (6), all inequalities obtained along of the proof becomes equalities. In particular it follows that $\left|\phi_{N}\right|=\langle\boldsymbol{N}, \boldsymbol{h}\rangle=0$ and either $|\boldsymbol{T}|=|\phi|=0$ or $\boldsymbol{H}=0$. In the first case, $\Sigma^{2}$ is a $\mathcal{H}$-surface satisfying the assumptions of [6, Corollary 3.3] so it is totally geodesic. Therefore, either it is isometric to a slice $\mathbb{S}^{2} \times\left\{t_{0}\right\}$ in the case $\boldsymbol{n}=2$, or to a totally geodesic sphere $\mathbb{S}^{2}$ in a certain $\mathbb{S}^{3} \times\left\{t_{0}\right\}$. For the second case, since $\boldsymbol{H}=0$, we must have that $\Sigma^{2}$ is a parallel surface of $\mathbb{S}^{2} \times \mathbb{R}$. On the one hand, since $\left|\phi_{N}\right|=\langle\boldsymbol{N}, \boldsymbol{h}\rangle=0$ it implies that $\boldsymbol{A}_{\boldsymbol{N}}=0$. Consequently it is not hard to see from the Codazzi equation that $T=0$, so $\Sigma^{2}$ is a minimal surface in a slice of $\mathbb{S}^{n} \times \mathbb{R}$. For the case where $\Sigma^{2}$ can be isometrically immersed in a certain $\mathbb{S}^{3} \times\left\{t_{0}\right\}$, by [4] we have that $\Sigma^{2}$ is isometric to a Clifford torus $\mathbb{S}^{1}(1 / \sqrt{2}) \times \mathbb{S}^{1}(1 / \sqrt{2})$ in $\mathbb{S}^{3} \times\left\{t_{0}\right\}$ for some $t_{0} \in \mathbb{R}$. In other case, observe that for $|\phi|^{2}=|\sigma|^{2}$, the equality in (1) becomes

$$
\begin{equation*}
\int_{\Sigma}|\sigma|^{2}\left(\frac{3}{2}|\sigma|^{2}-2\right) d \Sigma=0 \tag{7}
\end{equation*}
$$

Therefore, from [5, Theorem 1], $\Sigma^{2}$ is isometric to a Veronese surface in $\mathbb{S}^{4} \times\left\{t_{0}\right\}$, for some $t_{0} \in \mathbb{R}$.

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