

Structural stability for C^2 –diffeomorphisms

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Abstract

This work has as goal to present a proof of structural stability for C^2 diffeomorphisms which are axiom A and satisfy the strong transversality condition defined on a smooth, compact, boundaryless manifold.

Results and discussion

We say that $f, g \in \text{Diff}^r(M)$, $r > 1$, are *topologically conjugated* if there is a homeomorphism $\phi : M \rightarrow M$ such that $g = \phi \circ f \circ \phi^{-1}$. A C^r map f is *C^m –structurally stable* ($1 \leq m \leq r$) if there is a neighborhood U of f in the C^m topology such that for every map $g \in U$ is topologically conjugated f .

Definition 1. A point $x \in M$ is *nonwandering* if for any neighborhood U of x , there exists $n > 0$ such that $f^n(U) \cap U \neq \emptyset$. We denote by $\Omega(f)$ the set of nonwandering points of f .

Definition 2. A map $f \in \text{Diff}^r(M)$ satisfies *Axiom A* if $\Omega(f)$ is a hyperbolic and $\Omega(f) = \text{Per}(f)$.

Definition 3. We say that f satisfies the *strong transversality condition* if

$$E_x^s + E_x^u = T_x M,$$

for all $x \in M$, where $E_x^\sigma = E^\sigma \cap T_x M$.

Theorem 1. (Robbin, 71) A diffeomorphism $f \in \text{Diff}^2(M)$ that satisfies axiom A and the strong transversality condition is C^1 –structurally stable.

Robbin's condition

Consider a homeomorphism $\phi : M \rightarrow M$ satisfying $g \circ \phi = \phi \circ f$, for g C^1 –close to f , we can rewrite this equation as follows: $f^{-1} \circ g \circ \phi = f^{-1} \circ \phi \circ f$. Since $f^{-1} \circ g$ is close to the identity in the C^1 topology, there is $Y \in \mathfrak{X}^1(M)$ such that $f^{-1} \circ g = \exp(Y)$, where $\exp : TM \rightarrow M$ is the exponential map. As we want ϕ close to the identity, $\phi = \exp(X)$, for some $X \in \mathfrak{X}^0(M)$. So $g \circ \phi = \phi \circ f$ assumes the following form

$$(\text{Id} - f^\#)X = R_Y(X), \quad (1)$$

where Id is the identity operator, $f^\#$ is the linear operator induced by f defined in the Banach space $\mathfrak{X}^0(M)$ and R_Y is a nonlinear operator with small lipschitz constant.

Assuming that $(\text{Id} - f^\#)$ has a right inverse J , we can rewrite (1),

$$X = J R_Y(X). \quad (2)$$

Thus, the problem of finding a function ϕ that satisfies $g \circ \phi = \phi \circ f$ becomes the problem of finding a fixed point for a certain operator and choosing J appropriately such that $\phi = \exp(X)$ is a homeomorphism.

Definition 4. We say that a vector field $X \in \mathfrak{X}^0(M)$ is *d_f –Lipschitz* if for every letter (φ, U) in M , there is a $K \geq 0$ such that

$$|X_\varphi(x) - X_\varphi(y)| \leq K d_f(x, y),$$

where $X_\varphi : U \rightarrow \mathbb{R}^n$ such that $d\varphi_x X_x = (\varphi(x), X_\varphi(x))$. We denote by $\mathfrak{X}_f(M)$ the set of all fields d_f –lipschitz in M .

Definition 5. Let $f : M \rightarrow M$ be a C^2 diffeomorphism. We say that f satisfies *Robbin's condition* if there is a continuous linear operator $J : \mathfrak{X}^0(M) \rightarrow \mathfrak{X}^0(M)$ such that J is the right inverse of operator $(\text{Id} - f^\#)$ and $\mathfrak{X}_f(M)$ is J –invariant.

Theorem 2. If $f \in \text{Diff}^2(M)$ satisfies Robbin's condition, then f is structurally stable.

Locally hyperbolic

Definition 6. Let $N \subseteq M$ be an open set and $E \subseteq TN$ be a continuous subbundle. We say that E is *d_f –Lipschitz* if for every $x \in N$ and any neighborhood U of x , there are vector fields $X_1, \dots, X_k \in \mathfrak{X}_f(M)$, such that $X_1(y), \dots, X_k(y)$ is a basis of E_y , for all $y \in U$.

Definition 7. We say that f is *locally hyperbolic* if there are open subsets $Z_1, \dots, Z_l, W_1, \dots, W_l \subset M$, subbundles E_i^u, E_i^s of TZ_i^f , where $i = 1, \dots, l$, a Riemannian metric $\|\cdot\|$ and $0 < \lambda < 1$ such that for $i, j = 1, \dots, l$, $\sigma = s, u$

1. $\overline{W}_i \subseteq Z_i$;
2. $M = \cup_i^l W_i^f$;
3. W_i is not revisited by f ;
4. $Z_i \cap Z_j = \emptyset$, for $i \neq j$;
5. E_i^σ is d_f –lipschitz;
6. E_i^σ is df –invariant;
7. $TZ_i^f = E_i^s \oplus E_i^u$;
8. $\|df_x \cdot v\| \leq \lambda \|v\|$, for $v \in E_{i,x}^s$, where $x \in Z_i$,
 $\|df_x^{-1} \cdot v\| \leq \lambda \|v\|$, for $v \in E_{i,x}^u$, where $x \in Z_i$;
9. $E_{i,x}^s \subseteq E_{j,x}^s$ and $E_{j,x}^u \subseteq E_{i,x}^u$ to $x \in Z_i^{f+} \cap Z_j^{f-}$.

Theorem 3. Let $f : M \rightarrow M$ be a C^2 diffeomorphism. If f is locally hyperbolic, then f satisfies Robbin's condition.

Let $\theta_1, \dots, \theta_l$ be a partition of unity subordinate to the coverage W_1^f, \dots, W_l^f of M . Let $X \in \mathfrak{X}^0(M)$. For $i = 1, \dots, l$, we write

$$\theta_i X = X_{i,s} + X_{i,u}.$$

We now define the field

$$J(X) = \sum_{i=1}^l (J_{i,u}(X_{i,u}) + J_{i,s}(X_{i,s})). \quad (3)$$

Since $J_{i,s}(X)$ and $J_{i,u}(X)$ converge uniformly, we have that $J(X)$ converges uniformly and $(\text{Id} - f^\#)J(X) = X$.

Theorem 4. If f satisfies Axiom A and the strong transversality condition, then f is locally hyperbolic.

Since f satisfies Axiom A, by Smale's Spectral Decomposition Theorem it is possible to write $\Omega(f) = \Omega_1 \cup \dots \cup \Omega_l$ where Ω_i is compact and f –invariant. Using the strong transversality condition it is possible to consider Z_i neighborhoods of Ω_i , thus the local hyperbolicity conditions are satisfied.

Conclusion

Given a C^2 diffeomorphism satisfying Axiom A with strong transversality, it is locally hyperbolic. This property ensures the Robbin's condition, which, in turn, guarantees C^1 structural stability.

Reference

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