

Moving Planes Method

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Abstract

As a first beautiful illustration of the power of the Maximum Principle, we will prove the following symmetry theorem, which plays an important role in the study of nonlinear elliptic and parabolic PDE.

Introduction

The method of moving planes is used in proving symmetry, in fact, x_1 direction for solutions of nonlinear elliptic equation $F(x, u, Du, D^2u) = 0$ in a bounded domain Ω in \mathbb{R}^n which is convex in the x_1 direction.

The essential ingredient in their use is the Maximum principle. In this method one point is the reflection of the other in a hyperplane $\{x_1 = \lambda\}$, and then, the plane is moved up to a critical position.

We choose a very simple example to illustrate such a method. The following result was first proved by Gidas, Ni and Nirenberg.

Theorem.1.

Suppose $u \in C(B_1) \cap C^2(B_1)$ is a positive solution of

$$\begin{aligned} \Delta u + f(u) &= 0 \text{ in } B_1 \\ u &= 0 \text{ on } \partial B_1 \end{aligned}$$

where f is locally Lipschitz in \mathbb{R} . Then u is radially symmetric in B_1 and $\frac{\partial u}{\partial r}(x) < 0$ for $x \neq 0$.

The original proof requires that solutions be C^2 up to the boundary. Here we give a method which does not depend on the smoothness of domains nor the smoothness of solutions up to the boundary.

Proof

Before stating the result let us first fix some notations. We will be moving planes in the x_1 -direction but of course also any other direction will do.

Some sets that will be used are:

The moving plane: $T_\lambda = \{x \in \mathbb{R}^n; x_1 = \lambda\}$;

The subdomain: $\Sigma_\lambda = \{x \in \Omega; x_1 > \lambda\}$;

The reflected point: $x_\lambda = (2\lambda - x_1, x_2, \dots, x_n)$;

the reflected subdomain: $\Sigma'_\lambda = \{x_\lambda; x \in \Sigma_\lambda\}$;

The starting value for λ : $\lambda_0 = \inf\{x_1; x \in \Omega\}$;

The maximal value for λ :

$\lambda_* = \inf\{\lambda; w_\mu < 0 \text{ on } \Sigma_\mu \text{ for all } \mu > \lambda\}$;

We will prove $u(x_1, y) < u(x_1^*, y)$ for any $x_1 > 0$ and $x_1^* < x_1$ with $x_1^* + x_1 > 0$.

Then by letting $x_1^* \rightarrow -x_1$, we get $u(x_1, y) \leq u(-x_1, y)$ for any x_1 .

Then by changing the direction $x_1 \rightarrow -x_1$, we get the symmetry.

In Σ_λ we define

$$w_\lambda(x) = u(x) - u(x_\lambda) \text{ for } x \in \Sigma_\lambda$$

Since Δ is x_1 -invariant, $u(x_\lambda)$ satisfies the same equation as u in Σ_λ :

$$\begin{aligned} \Delta u(x_\lambda) + f(u(x_\lambda)) &= 0 \text{ in } \Sigma_\lambda \\ \Delta w(x_\lambda) + f(u(x_\lambda)) - f(u) &= 0 \Leftrightarrow \Delta w(x_\lambda) + c_\lambda(x) \cdot w_\lambda = 0 \end{aligned}$$

where

$$c_\lambda(x) = \begin{cases} \frac{f(u(x_\lambda)) - f(u(x))}{u(x_\lambda) - u(x)} & \text{if } u(x_\lambda) \neq u(x) \\ 0 & \text{if } u(x_\lambda) = u(x) \end{cases}$$

The hypothesis that f is locally Lipschitz guarantees that $c_\lambda(x)$ is a bounded function, i.e.

$$|c_\lambda(x)| \leq Lip(f).$$

Then we have by The mean value theorem

$$\begin{aligned} \Delta w_\lambda + c_\lambda(x) &= 0 \text{ in } \Sigma_\lambda \\ w_\lambda &\leq 0 \text{ and } w_\lambda \neq 0 \text{ on } \partial \Sigma_\lambda \end{aligned}$$

Moreover $\lambda < \lambda^*$ we have $u(x_\lambda) \leq u(x)$ on $\partial \Omega \cap \partial \Sigma_\lambda$ and $u(x_\lambda) = u(x)$ on $\Omega \cap \partial \Sigma_\lambda$.

Hence $w_\lambda \leq 0$ on $\partial \Sigma_\lambda$

The two basic ingredients in the proof are the maximum principle for small domains and the strong maximum principle for nonpositive functions.

Let $\delta = \delta(n, K) > 0$ be the constant from the maximum principle in small domains.

We will divide the proof in two steps:

1. The moving process can start, that is, $\exists \epsilon_1$ such that $w_\lambda < 0$ on Σ_λ if $\lambda \in (a - \epsilon_1, a)$.

Let $\epsilon_1 > 0$ be small enough such that $|\Sigma_\lambda| < \delta$ if $\lambda \in (a - \epsilon_1, a)$.

We know that $w_\lambda = 0$ on $T_\lambda \cap \partial \Sigma_\lambda$ e $w_\lambda < 0$ on $\partial \Omega \cap \partial \Sigma_\lambda$, so we can use (1) and (2) with $z = w_\lambda$

$$\Delta w_\lambda + c_\lambda(x)w_\lambda = 0 \text{ in } \Sigma_\lambda \quad (1)$$

$$w_\lambda \leq 0 \text{ on } \partial \Sigma_\lambda \quad (2)$$

$$\Rightarrow w_\lambda \leq 0 \text{ in } \Sigma_\lambda$$

By the strong M.P. $w_\lambda \equiv 0$ or $w_\lambda < 0$ on Σ_λ .

But $w_\lambda \equiv 0$ is not possible, because if $w_\lambda \equiv 0$ for some $\lambda \in (a - \epsilon_1, a)$ then $u(x) = 0$ for $x \in \partial(\Sigma'_\lambda \cup \Sigma_\lambda)$ and moreover, since part of this boundary, $\Omega \cap \partial(\Sigma'_\lambda \cup \Sigma_\lambda)$ lies inside Ω it contradicts $u > 0$ in Ω .

Thus $w_\lambda < 0$ in Σ_λ .

This implies in particular that w_λ assumes along $\partial \Sigma_\lambda \cap \Omega$ its maximum in Σ_λ .

We can start moving the hyperplanes.

2. If we have reached position $\lambda > 0$, we can move a bit to the left, our objective is $\lambda_* = 0$.

The conclusion that $\frac{\partial}{\partial x_1} u(x) < 0$ for $x \in \Sigma_\lambda^*$ follows from the fact that $w_\lambda(x) < 0$ on Σ_λ for all $\lambda \in (\lambda_0, \lambda^*)$ and by Hopf's boundary point Lemma $\frac{\partial}{\partial x_1} u(x) = 1/2 \frac{\partial}{\partial x_1} w_\lambda(x) < 0$ on $T_\lambda \cap \Omega$

Proof of Theorem

From the previous theorem we find that $x_1 \frac{\partial}{\partial x_1} u(x) < 0$ for $x \in B_R(0)$ with $x_1 \neq 0$. Hence $\frac{\partial}{\partial x_1} u(x) = 0$ for $x_1 = 0$. Since Δ is radially invariant this holds for every direction and we find $\frac{\partial}{\partial \tau} u(x) = 0$ in $B_R(0)$ for any tangential direction. In other words, u is radially symmetric. Since $\frac{\partial}{\partial |x|} u(x) = \frac{\partial}{\partial r} u(r, 0, \dots, 0)$ for $0 < r = |x| < R$ the second claim follows from $\frac{\partial}{\partial x_1} u(x) < 0$ for $x \in B_R(0)$ with $x_1 > 0$

Observation 1. This result is also valid if we replace the Laplacian by an operator invariant with respect to reflections in the x_1 direction.

Observation 2. Applying Lemma.1. in all directions we obtain Theorem 1.

Referências

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