Feedback Control Principles for Biological Control of Dengue Vectors

Pierre-Alexandre Bliman¹

 1 Sorbonne Université, Université Paris-Diderot SPC, Inria, CNRS, Laboratoire Jacques-Louis

Lions, équipe Mamba, F-75005 Paris, France

Controlling diseases such as dengue fever, chikungunya or zika by spreading the parasitic bacterium *Wolbachia* in mosquito populations which are their vectors, is considered a promising tool to reduce their spread. While description of the conditions of such experiments has received ample attention from biologists, entomologists and applied mathematicians, the effective scheduling of the releases remains an interesting issue for Control theory. Having in mind the important uncertainties on the dynamics of the two populations in interaction, we attempt here to identify general ideas for building release strategies, applicable to various models and situations. These principles are exemplified by two interval observer-based feedback control laws whose stabilizing properties are demonstrated when applied to an ODE model retrieved from [1]. Crucial use is made of the theory of monotone systems [3]. See [2] for details.

References

- P.-A. BLIMAN, M.S. ARONNA, F.C. COELHO, M.A.H.B. DA SILVA, *Ensuring successful introduction of* Wolbachia *in natural populations of* Aedes aegypti *by means of feedback control*, J. Math. Biol. 76(5):1269–1300, 2018
- [2] P.-A. BLIMAN, Feedback Control Principles for Biological Control of Dengue Vectors, Proc. of European Control Conference, Naples (Italy), June 25-28, 2019
- [3] H.L. SMITH, Monotone dynamical systems: an introduction to the theory of competitive and cooperative systems, Mathematical surveys and monographs vol 41, American Mathematical Society, 1995