

Local convergence analysis of Inexact Newton method with relative residual error tolerance under majorant condition in Riemannian Manifolds

T. Bittencourt ^{*} O. P. Ferreira[†]

January 9, 2014

Abstract

A local convergence analysis of Inexact Newton's method with relative residual error tolerance for finding a singularity of a differentiable vector field defined on a complete Riemannian manifold, based on majorant principle, is presented in this paper. We prove that under local assumptions, the inexact Newton method with a fixed relative residual error tolerance converges Q -linearly to a singularity of the vector field under consideration. Using this result we show that the inexact Newton method to find a zero of an analytic vector field can be implemented with a fixed relative residual error tolerance. In the absence of errors, our analysis retrieve the classical local theorem on the Newton method in Riemannian context.

Keywords: Inexact Newton's method, majorant principle, local convergence analysis, Riemannian manifold.

^{*}IME/UFG, CP-131, CEP 74001-970 - Goiânia, GO, Brazil (Email: tiberio.b@gmail.com). This author was supported by CAPES.

[†]IME/UFG, CP-131, CEP 74001-970 - Goiânia, GO, Brazil (Email: orizon@mat.ufg.br). This author was supported by CNPq Grants 302024/2008-5, 480101/2008-6 and 473756/2009-9, PRONEX-Optimization(FAPERJ/CNPq) and FUNAPE/UFG.

Our goal is to prove in Riemannian manifold context the following version of Inexact Newton method with relative residual error tolerance under majorant condition.

Theorem 1. *Let \mathcal{M} be a Riemannian manifold, $\Omega \subseteq \mathcal{M}$ an open set and $X : \Omega \rightarrow T\mathcal{M}$ a continuously differentiable vector field. Let $p_* \in \Omega$, $R > 0$ and $\kappa := \sup\{t \in [0, R) : B_t(p_*) \subset \Omega\}$. Suppose that $X(p_*) = 0$, $\nabla X(p_*)$ is invertible and there exists an $f : [0, R) \rightarrow \mathbb{R}$ continuously differentiable such that*

$$\|\nabla X(p_*)^{-1}[P_{\zeta,1,0} \nabla X(p) - P_{\zeta,\tau,0} \nabla X(\zeta(\tau))P_{\zeta,1,\tau}]\| \leq f'(d(p_*, p)) - f'(\tau d(p_*, p)),$$

for all $\tau \in [0, 1]$, $p \in B_\kappa(p_*)$, where $\zeta : [0, 1] \rightarrow \mathcal{M}$ is a minimizing geodesic from p_* to p and

h1) $f(0) = 0$ and $f'(0) = -1$;

h2) f' is strictly increasing.

Let $0 \leq \vartheta < 1/K_{p_*}$, $\nu := \sup\{t \in [0, R) : f'(t) < 0\}$, $\rho := \sup\{\delta \in (0, \nu) : [(1 + \vartheta)|t - f(t)/f'(t)|/t + \vartheta] < 1/K_{p_*}, t \in (0, \delta)\}$ and

$$r := \min\{\kappa, \rho, r_{p_*}\}.$$

Then the sequence generated by the Inexact Newton method for solving $X(p) = 0$ with starting point $p_0 \in B_r(p_*) \setminus \{p_*\}$ and residual relative error tolerance θ ,

$$p_{k+1} = \exp_{p_k}(S_k), \quad \|X(p_k) + \nabla X(p_k)S_k\| \leq \theta \|X(p_k)\|, \quad k = 0, 1, \dots, \quad (1)$$

$$0 \leq \text{cond}(\nabla X(p_*))\theta \leq \vartheta / [2/|f'(d(p_*, p_0))| - 1], \quad (2)$$

is well defined (for any particular choice of each $S_k \in T_{p_k}M$), the sequence $\{p_k\}$ is contained in $B_r(p_*)$ and converges to the point p_* which is the unique zero of X in $B_\sigma(p_*)$, where $\sigma := \sup\{t \in (0, \kappa) : f(t) < 0\}$, and we have that:

$$d(p_*, p_{k+1}) \leq K_{p_*} \left[(1 + \vartheta) \frac{\left| d(p_*, p_k) - \frac{f(d(p_*, p_k))}{f'(d(p_*, p_k))} \right|}{d(p_*, p_k)} + \vartheta \right] d(p_*, p_k), \quad k = 0, 1, \dots, \quad (3)$$

and $\{p_k\}$ converges linearly to p_* . If, in addition, the function f satisfies the following condition

h3) f' is convex,

then there holds

$$d(p_*, p_{k+1}) \leq K_{p_*} \left[(1 + \vartheta) \frac{\left| d(p_*, p_0) - \frac{f(d(p_*, p_0))}{f'(d(p_*, p_0))} \right|}{d^2(p_*, p_0)} d(p_*, p_k) + \vartheta \right] d(p_*, p_k), \quad k = 0, 1, \dots. \quad (4)$$

as a consequence, the sequence $\{p_k\}$ converges to p_* with linear rate as follows

$$d(p_*, p_{k+1}) \leq K_{p_*} \left[(1 + \vartheta) \frac{\left| d(p_*, p_0) - \frac{f(d(p_*, p_0))}{f'(d(p_*, p_0))} \right|}{d(p_*, p_0)} + \vartheta \right] d(p_*, p_k), \quad k = 0, 1, \dots \quad (5)$$