

Theory of metric Lie groups and **H**-surfaces in homogeneous **3**-manifolds.

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Based on joint work with Mira, Pérez, Ros and Tinaglia.

Definition

A **2**-dimensional submanifold with constant mean curvature $\mathbf{H} \geq 0$ in a Riemannian **3**-manifold is called an **H-surface**.

Definition

If the isometry group of a Riemannian manifold **Y** acts transitively, then **Y** is called **homogeneous**.

Definition

A Lie group with left invariant metric is called a **metric Lie group**.

Notation and Language

- Y = simply connected homogeneous 3-manifold.
- X = simply connected 3-dimensional Lie group with left invariant metric (X is a **metric Lie group**).
- $H(Y) = \text{Inf}\{\max |H_M| : M = \text{immersed closed surface in } Y\}$, where $\max |H_M|$ denotes max of absolute mean curvature function H_M .
- The number $H(Y)$ is called the **critical mean curvature** of Y .
- $\text{Ch}(Y) = \text{Inf}_{K \subset Y \text{ compact}} \frac{\text{Area}(\partial K)}{\text{Volume}(K)} = \text{Cheeger constant of } Y$.

Goals of Lecture 3

- Classification of algebraic open book decompositions.
- The left invariant Lie group Gauss map and the embeddedness problem for H -spheres.
- The **Meeks-Tinaglia** curvature and radius estimates for H -disks.
- Existence and uniqueness of H -spheres in X (**Meeks-Mira-Pérez-Ros**).
- Discuss various conjectures on embedded H -surfaces in Y .

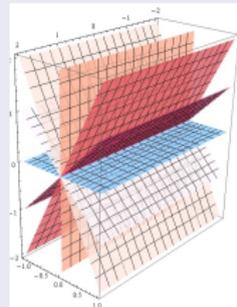
Definition

- Let Γ be a 1-parameter subgroup of X .
- We will call a foliation $\mathcal{B} = \{L(\theta) \mid \theta \in [0, 2\pi)\}$ of $X - \Gamma$ an **algebraic open book decomposition of X** if the set $H(\theta) = L(\theta) \cup \Gamma \cup L(\pi + \theta)$ is a subgroup for each $\theta \in \mathbb{R}$.
- We call $L(\theta)$ a **leaf**, Γ the **binding** and $H(\theta)$ a **subgroup** of the algebraic open book decomposition \mathcal{B} .

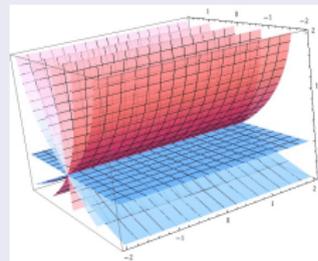
Example

- Let $X = \mathbb{R}^3$ and Γ be the z -axis.
- Then the foliation \mathcal{B} of $\mathbb{R}^3 - \Gamma$ by half planes with boundaries Γ is an algebraic open book decomposition of \mathbb{R}^3 .

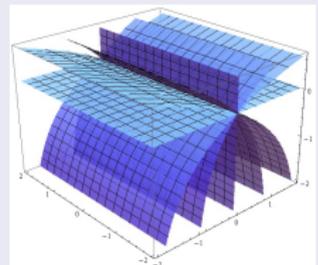
The unique **algebraic open book** decomposition of Nil_3 , where all subgroups are minimal planes. Here the binding Γ is the x -axis.



Algebraic open book decomposition of Sol_3 , where all subgroups are minimal and the only planar leaves are the (x, y) and (x, z) -planes. Here the binding Γ is the x -axis.



Algebraic open book decomposition of Sol_3 , where all subgroups are minimal and the only planar leaves are the (x, y) and (y, z) -planes. Here the binding Γ is the y -axis.



Examples of algebraic open book decomposition of a semidirect product.

- Let $\mathbf{G} = \mathbb{R}^2 \rtimes_{\mathbf{A}} \mathbb{R}$, where $\mathbf{A} = \begin{pmatrix} 1 & 0 \\ 0 & b \end{pmatrix}$.

- Note that when $b = 0$, $\mathbb{R}^2 \rtimes_{\mathbf{A}} \mathbb{R}$ is isometric to $\mathbb{H} \times \mathbb{R}$.

- Let E_1, E_2, E_3 be the usual basis for $\mathbf{L}(\mathbf{G})$ where:

$$[E_1, E_2] = 0, \quad [E_3, E_1] = E_1, \quad [E_3, E_2] = bE_2.$$

- Special normal \mathbb{R}^2 -subgroup $\mathbf{J}_1(\infty) = \mathbf{J}_2(\infty) = \mathbb{R}^2 \rtimes_{\mathbf{A}} \{0\}$ corresponds to the distribution $\{aE_1 + cE_2 \mid a, c \in \mathbb{R}\}$.
- \mathbb{H} -subgroups, $b \neq 0$. $\mathbf{J}_1(\lambda) = \{(x, \lambda(e^z - 1), z) \mid x, z \in \mathbb{R}\}$ correspond to distributions $\Delta_{\mathbf{d}} = \{aE_1 + c(E_3 + \mathbf{d}E_2) \mid a, c \in \mathbb{R}\}$.
- \mathbb{H} -subgroups, $b \neq 0$. $\mathbf{J}_2(\lambda) = \{(\lambda(e^z - 1), y, z) \mid x, z \in \mathbb{R}\}$ correspond to distributions $\Delta_{\mathbf{d}} = \{aE_2 + c(E_3 + \mathbf{d}E_2) \mid a, c \in \mathbb{R}\}$.
- \mathbb{H} -subgroups, $b = 0$. $\mathbf{J}_1(\lambda) = \{(x, \lambda z, z) \mid x, z \in \mathbb{R}\}$ correspond to distributions $\Delta_{\mathbf{d}} = \{aE_1 + c(E_3 + \mathbf{d}E_2) \mid a, c \in \mathbb{R}\}$.
- \mathbb{R}^2 -subgroups, $b = 0$. $\mathbf{J}_2(\lambda) = \{(\lambda(e^z - 1), y, z) \mid y, z \in \mathbb{R}\}$ correspond to distributions $\Delta_{\mathbf{d}} = \{aE_2 + c(E_3 + \mathbf{d}E_1) \mid a, c \in \mathbb{R}\}$.

Example

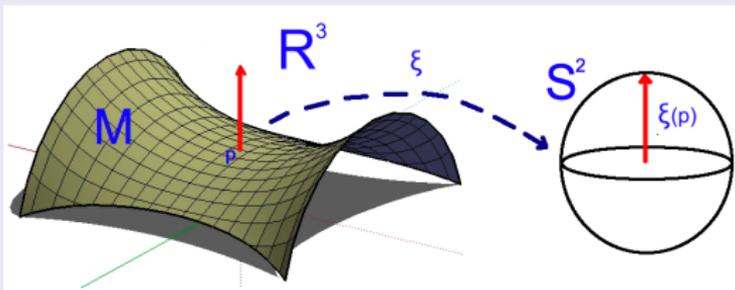
- The collection $\mathcal{B}_1 = \{J_1(\theta) \mid \theta \in \mathbb{S}^1 = \mathbb{R} \cup \{\infty\}\}$ consists of the subgroups of an algebraic open book decomposition of $\mathbb{R}^2 \rtimes_{\mathbf{A}} \mathbb{R}$ with binding the x -axis.
- The collection $\mathcal{B}_2 = \{J_2(\theta) \mid \theta \in \mathbb{S}^1 = \mathbb{R} \cup \{\infty\}\}$ consists of the subgroups of an algebraic open book decomposition of $\mathbb{R}^2 \rtimes_{\mathbf{A}} \mathbb{R}$ with binding the y -axis.

Theorem (Meeks-Mira-Pérez-Ros)

- A necessary and sufficient condition for a simply connected Lie group \mathbf{G} to admit 2 different open book decompositions is that it can be expressed as a semidirect product $\mathbb{R}^2 \rtimes_{\mathbf{A}} \mathbb{R}$, where \mathbf{A} is a diagonal matrix.
- These are the non-unimodular groups with invariant $\mathbf{D}(\mathbf{G}) < 1$, \mathbb{H}^3 and the unimodular group \mathbf{Sol}_3 .
- \mathbf{Nil}_3 and $\mathbf{G} \neq \mathbb{H}^3$ with $\mathbf{D}(\mathbf{G}) = 1$ each admit 1 such algebraic open book decomposition.
- The algebraic open books in the previous 3 items together with those given by planes in \mathbf{R}^3 are the only ones.

Definition (Left Invariant Gauss Map)

- Let $M \subset X$ be an oriented surface, S^2 be the unit sphere in $T_e X$ and $N(\mathbf{p})$ be the unit normal to M at \mathbf{p} .
- The **left invariant Gauss map** of M is the mapping $G: M \rightarrow S^2$, where $G(\mathbf{p})$ is the left translation of $N(\mathbf{p})$ from $T_{\mathbf{p}} X$ to $T_e X$.



Here $M \subset X$ is an oriented surface with unit normal vector field $N = \xi$. Then: $G: M \rightarrow S^2 \subset T_e X$ is defined by $G(\mathbf{p}) = \mathbf{p}^{-1}N(\mathbf{p})$.

The rank of the left invariant Gauss map; Meeks-Mira-Pérez-Ros

- If H is a 2-dimensional subgroup of X , then for any $a \in H$, $aH = H$, and so the left invariant Gauss map of H is constant.
- Let Σ be an H -surface in X .
- If the left invariant Gauss map of Σ has rank 0 at every point, then Σ is contained in some 2-dimensional subgroup of X (Lecture 4).
- If the left invariant Gauss map of Σ has rank 0 at some point p , then \exists some 2-dimensional subgroup of X with the same normal vector as Σ at p (see Lecture 4).
- So, if X is isomorphic to $SU(2)$, then the rank of the left invariant Gauss map of any H -surface is everywhere at least 1.
- If the left invariant Gauss map of Σ has rank 1 everywhere, then Σ is invariant under the left action of a 1-parameter subgroup of X .

Lemma (Transversality Lemma, Meeks-Mira-Pérez-Ros)

Suppose that S is an immersed sphere in an X and F is a 2-dimensional subgroup. If the left invariant Gauss map $G: S \rightarrow \mathbb{S}^2$ is a diffeomorphism, then:

- The set of left cosets of F which intersect S can be parameterized by the interval $[0, 1]$, i.e., $\{g(t)F \mid t \in [0, 1]\}$ are these cosets.
- Each of the cosets $g(0)F$ and $g(1)F$ intersects S in a single point.
- For $t \in (0, 1)$, $S \cap g(t)F$ is a connected immersed closed curve.

Proof.

- Note that the Gauss map of F has a constant value, and so, the Gauss maps of the left cosets of F have the same constant value.
- The set of left cosets $\{gF \mid g \in X\}$ is parameterized smoothly by \mathbb{R} .
- Let $\Pi: X \rightarrow \mathbb{R} = \{gF \mid g \in X\}$ be the related smooth quotient map.
- Since the Gauss maps of the leaves of level sets for Π have the same constant unit normal and the Gauss map of S is a diffeomorphism, $\Pi|_S$ can have at most 2 critical points, 1 maximum and 1 minimum.
- Elementary Morse theory implies all of the statements hold.



Theorem (Meeks-Mira-Pérez-Ros)

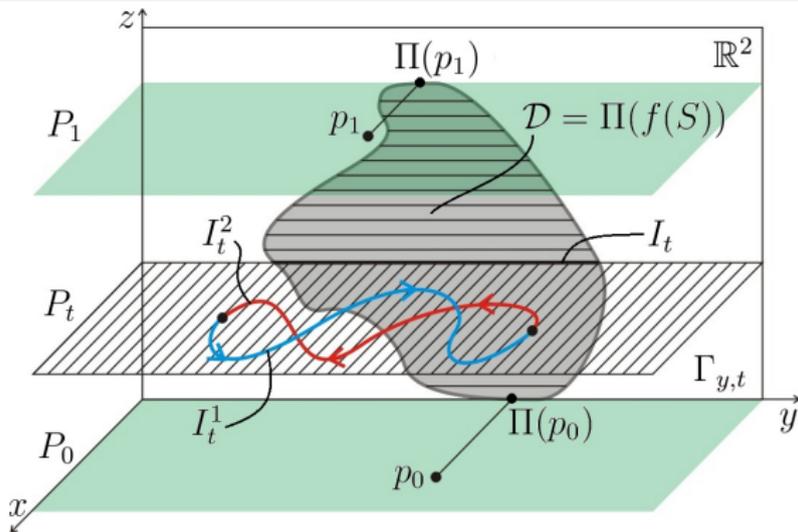
Suppose that X has an algebraic open book decomposition. If $f: S \rightarrow X$ is an immersed sphere in whose left invariant Gauss map $G: S \rightarrow \mathbb{S}^2$ is a diffeomorphism, then S is embedded.

Proof when X has 2 algebraic open book decomposition.

- By the previous theorem, $X = \mathbb{R}^2 \rtimes_A \mathbb{R}$ for some diagonal matrix A .
- The new Gauss map in this new metric, which we denote the same way, is still a diffeomorphism.
- Consider the algebraic open book decompositions $\mathcal{B}_1 = \{J_1(\theta) \mid \theta \in \mathbb{S}^1\}$ and $\mathcal{B}_2 = \{J_2(\theta) \mid \theta \in \mathbb{S}^1\}$ of $\mathbb{R}^2 \rtimes_A \mathbb{R}$ with bindings $\Gamma_1 = x$ -axis and $\Gamma_2 = y$ -axis, respectively.
- The theorem follows easily from the next assertion, since we can express S as the union of 2 "disjoint" disks which are graphs over the yz -plane; see the argument in the next slide.

Assertion

For $i = 1, 2$ and for each $a \in X$, $f^{-1}(a\Gamma_i)$ contains at most 2 points.



- Suppose the left coset P_t intersects transversely in the immersed curve $\mathbf{f}(S) \cap P_t$.
- For $i = 1, 2$ and for each $a \in \mathbf{X}$, $\mathbf{f}^{-1}(a\Gamma_i)$ contains at most **2** points.
- For $i = 1$, the immersed curve $\mathbf{f}(S) \cap P_t$ consists of two Jordan arcs I_t^1, I_t^2 with the same extrema.
- Hence, projection along Γ_1 represents Σ as a bigraph over the yz -plane.
- Also, projection along Γ_2 represents Σ as a bigraph over the xz -plane.
- So, Σ is embedded!!

Assertion

For $i = 1, 2$ and for each $a \in \mathbf{X}$, $\mathbf{f}^{-1}(a\boldsymbol{\Gamma}_i)$ contains at most 2 points.

Proof.

- Suppose that the assertion fails, assume $i = 1$ and let $\boldsymbol{\Gamma} = \boldsymbol{\Gamma}_1$.
- Then for some $a \in \mathbf{X}$, $a\boldsymbol{\Gamma}$ intersects \mathbf{S} transversely with $\mathbf{f}^{-1}(a\boldsymbol{\Gamma}) = \{p_1, \dots, p_{2n}\} \subset \mathbf{S}$ for some $n \geq 2$.
- After left translating \mathbf{S} by a^{-1} , assume that $a\boldsymbol{\Gamma} = \boldsymbol{\Gamma}$.
- Since each subgroup of \mathcal{B}_1 intersects \mathbf{S} in at least 4 points, the Transversality Lemma implies each leaf L_θ intersects \mathbf{S} transversely.
- The normal variational vector field ∂_θ for \mathcal{B}_1 defined on $\mathbf{X} - \boldsymbol{\Gamma}$ induces a nonzero tangential vector field ∂_θ^T on $\mathbf{S} - \mathbf{f}^{-1}(\boldsymbol{\Gamma})$.
- Since \mathbf{f} is transverse to the binding $\boldsymbol{\Gamma}$ of \mathcal{B}_1 , the index of ∂_θ^T is $+1$ at each of the points in $\{p_1, \dots, p_{2n}\}$.
- By the Hopf index theorem, the Euler characteristic of \mathbf{S} is $2n \geq 4$.
- This is a contradiction since the Euler characteristic of \mathbf{S} is 2. □

Theorem (Meeks-Mira-Pérez-Ros)

Let X be a 3-dimensional metric Lie group. Then:

- 1 X admits an open book decomposition **iff** it is isomorphic to \mathbb{R}^3 , \mathbb{H}^3 , Nil_3 , Sol_3 , or to a non-unimodular Lie group with D -invariant $D \leq 1$.
- 2 If X admits an algebraic open book decomposition and $f: S \rightarrow X$ is an immersed sphere whose left invariant Gauss map of is a diffeomorphism, then f is injective.
- 3 The left invariant Gauss map of H -spheres in X are diffeomorphisms.
- 4 H -spheres in homogeneous 3-manifolds are always Alexandrov embedded (bound submersed 3-balls) except for the minimal spheres $S^2(\kappa) \times \{t\}$ in $S^2(\kappa) \times \mathbb{R}$.

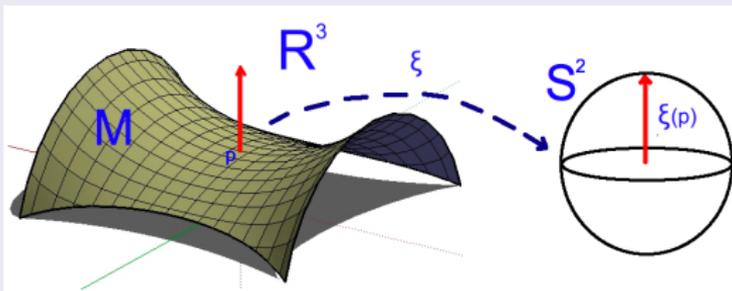
Remark

The fact that the Gauss map of an H -sphere in X is a diffeomorphism in item 4 in the above theorem depends on proving that H -spheres always have index 1.

Conjecture (Alexandrov Embeddedness Conjecture,
Meeks-Mira-Pérez-Ros)

- If Y be a simply connected, homogeneous 3-manifold not diffeomorphic to \mathbb{S}^3 , then H -spheres in Y are embedded.
- Furthermore, if Y is diffeomorphic to \mathbb{R}^3 , then compact Alexandrov embedded H -surfaces in Y are spheres.

Definition (Second Fundamental Form/Shape Operator)



Let M be an oriented surface in \mathbb{R}^3 , let ξ be the unit vector field normal to M :

$$A = -d\xi: T_p M \rightarrow T_{\xi(p)} S^2 \simeq T_p M$$

is the **shape operator** of M .

Introduction to the theory of CMC surfaces.

Definition

- The eigenvalues k_1, k_2 of \mathbf{A}_p are the **principal curvatures** of \mathbf{M} at p .
- $\mathbf{K}_G = \det(\mathbf{A}) = k_1 k_2$ is the **Gauss curvature**.
- $\mathbf{H} = \frac{1}{2} \text{Trace}(\mathbf{A}) = \frac{k_1 + k_2}{2}$ is the **mean curvature**.
- $\mathbf{K}_M = k_1 k_2$ is the **Gaussian curvature**.
- $|\mathbf{A}| = \sqrt{k_1^2 + k_2^2}$ is the **norm of the shape operator**.

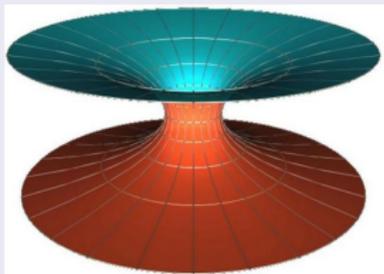
Gauss equation

$$4\mathbf{H}^2 = |\mathbf{A}|^2 + 2\mathbf{K}_G \quad (\mathbf{K}_G = \text{Gaussian curvature})$$

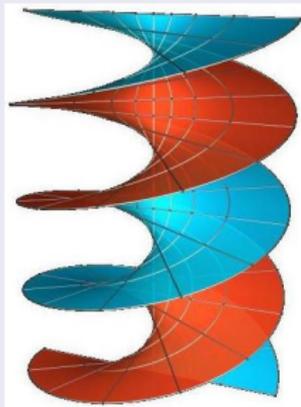
Introduction to the theory of CMC surfaces.

Theorem

An H -surface M is a **minimal surface** $\iff H \equiv 0 \iff M$ is a critical point for the area functional under compactly supported variations.



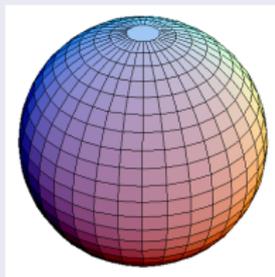
• Catenoid



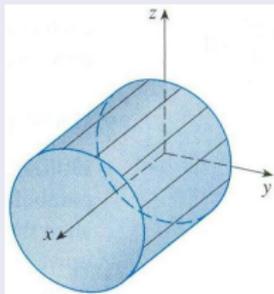
• Helicoid

Theorem

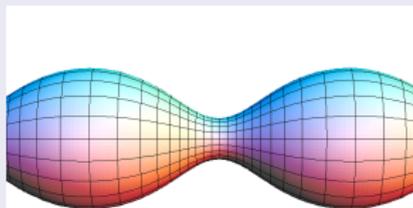
M is a **H-surface** $\iff M$ is a critical point for the area functional under compactly supported variations **preserving the volume**.



• Sphere



• Cylinder



• Delaunay surfaces

Uniqueness, existence, index and embeddedness of H -spheres in \mathbb{R}^3 .

Let M be a closed (compact without boundary) H -surface in \mathbb{R}^3 :

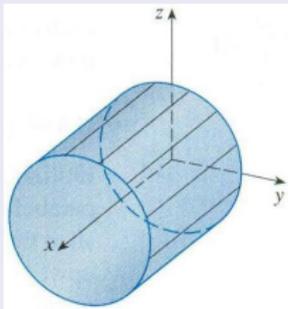
- M is **not** minimal. (coordinate functions cannot be harmonic)
- M has **genus 0** \iff it is a round sphere (1951, **Hopf**).
- M is **embedded** \iff it is a round sphere (1956, **Alexandrov**).
- **Index**(M) = 1 \iff M is a round sphere (1984, **Barbosa-do Carmo**).

New uniqueness results for CMC surfaces.

Question

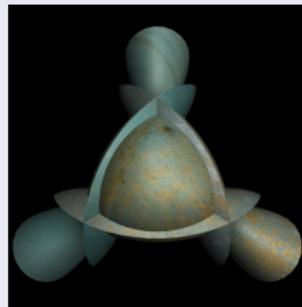
Is the round sphere the only complete simply connected surface **embedded** in \mathbf{R}^3 with **non-zero** constant mean curvature?

NOT simply connected



- Cylinder

NOT embedded



- Smyth surface

Answer (Meeks-Tinaglia)

Yes!

New uniqueness results for CMC surfaces.

Theorem (Meeks-Tinaglia)

Round spheres are the only complete simply connected surfaces **embedded** in \mathbf{R}^3 with non-zero constant mean curvature.

1997, **Meeks** for **properly embedded**.

Corollary

Let M be a complete simply connected H -surface **embedded** in \mathbf{R}^3 .
Then M is either

a plane, a helicoid **or** a round sphere.

(2008, **Colding-Minicozzi** and **Meeks-Rosenberg** for $H = 0$)

Definition

A **1-disk** is a compact disk **embedded** in \mathbf{R}^3 with constant mean curvature **1**.

Theorem (Radius Estimate, Meeks-Tinaglia)

There exists a universal constant \mathbf{R} such that if \mathbf{M} is a **1-disk**, then \mathbf{M} has **radius** less than \mathbf{R} , i.e.,

$$\forall \mathbf{p} \in \mathbf{M}, \quad \text{dist}_{\mathbf{M}}(\mathbf{p}, \partial\mathbf{M}) < \mathbf{R}.$$

In particular, if \mathbf{M} is a complete simply connected $\mathbf{H} = \mathbf{1}$ surface embedded in \mathbf{R}^3 , then:

Radius Estimate $\implies \mathbf{M}$ is compact $\implies \mathbf{M}$ is an embedded sphere.

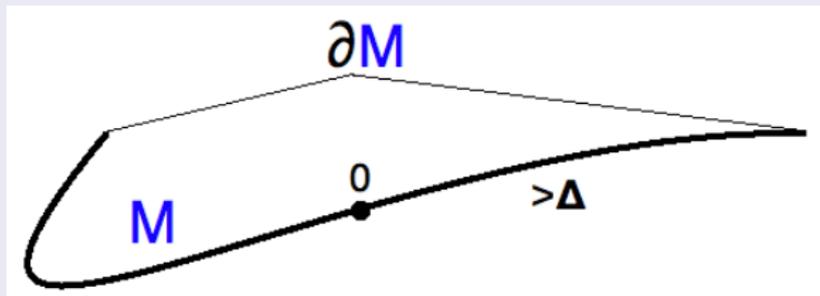
Hopf or Alexandrov Theorems $\implies \mathbf{M}$ is a **round sphere**.

The Radius Estimate is a **trivial** consequence of the following Intrinsic Curvature Estimate.

Theorem (Intrinsic Curvature Estimate, Meeks-Tinaglia)

- Let Y be a homogeneously regular **3**-manifold with absolute sectional curvature less than $K \geq 0$.
- Given $\Delta > 0$ there exist a universal constant $C = C(\Delta, K)$ such that:
- If M is an **H**-disk in Y with $0 \in M$, $\text{dist}_M(0, \partial M) > \Delta$ and $H \geq 1$, then

$$|A_M|(0) \leq C.$$



Theorem (Radius/Curvature Estimate, Meeks-Tinaglia)

- Suppose that $X = \mathbb{H}^3$.
- There exists a universal constant R such that if M is an H -disk and $H > H(X)$, then M has radius less than R , i.e.,

$$\forall p \in M, \quad \text{dist}_M(p, \partial M) < R.$$

- Complete embedded H -surfaces in X with $H > 0$ have bounded second fundamental forms and are properly embedded when $H > 1$.

In particular, if M is a complete simply connected $H > 1$ surface embedded in \mathbb{H}^3 , then:

Radius Estimate $\implies M$ is compact $\implies M$ is an embedded sphere.

Hopf or Alexandrov Theorems $\implies M$ is a **round geodesic sphere**.

Conjecture (Radius/Curvature Estimates, Meeks-Tinaglia)

- There exists a universal constant R such that if M is an embedded H -disk with $H > H(Y)$, then M has radius less than R , i.e.,

$$\forall p \in M, \quad \text{dist}_M(p, \partial M) < R.$$

- Complete embedded H -surfaces in Y with $H > 0$ have bounded second fundamental forms.
- Every complete embedded H -surface of finite topology in Y is properly embedded, whenever $H \geq H(Y)$.

Theorem (Classification Theorem for H -spheres, Meeks-Mira-Pérez-Ros)

Suppose X is a simply connected 3-dimensional metric Lie group.

- X is diffeomorphic to $\mathbb{R}^3 \implies$ the moduli space of H -spheres in X is parameterized by the mean curvature values H in $(H(X), \infty)$.
- X is diffeomorphic to $\mathbb{S}^3 \implies$ the moduli space of H -spheres in X is parameterized by the mean curvature values H in $[0, \infty)$.
- X diffeomorphic to $\mathbb{S}^3 \implies$ the areas of all H -spheres form a half-open interval $(0, A(X)]$.
- H -spheres in X are **Alexandrov embedded** with **index 1**, **nullity 3**.

- The proof of the above theorem will be the focus of Lecture 4.
- We place it here in order to discuss the following related conjectures.

Conjecture (Index 1 Conjecture, Meeks-Mira-Pérez-Ros)

When X is diffeomorphic to \mathbb{R}^3 , then every compact H -surface in X with index 1 is a sphere. In particular, solutions to the isoperimetric problem in such an X are spheres.

Conjecture (Isoperimetric Domains Conjecture, Meeks-Mira-Pérez-Ros)

If X is diffeomorphic to \mathbb{R}^3 , then:

- 1 Isoperimetric surfaces (boundaries of isoperimetric domains) in X are spheres.
- 2 For each fixed volume V_0 , solutions to the isoperimetric problem in X for volume V_0 are unique up to left translations in X .

Conjecture (Topological Existence Conjecture, Meeks)

- If $X \approx \mathbb{R}^3$ and $H < H(X)$, then X admits properly embedded H -surfaces of every possible topology.
- If $X \approx \mathbb{R}^3$ and $H > H(X)$, then X admits properly embedded H -surfaces of every possible topology, except for finite genus with 1 end or finite positive genus with 2 ends which it never admits.

Conjecture (Topological Uniqueness Conjecture, Meeks)

If M_1, M_2 are two diffeomorphic, connected and properly embedded H -surfaces of finite topology in X with $H = H(X)$, then there exists a diffeomorphism $f: X \rightarrow X$ with $f(M_1) = M_2$.

Meeks-Frohman

If M_1, M_2 are two diffeomorphic, connected and properly embedded minimal surfaces in $Y = \mathbb{S}(\kappa) \times \mathbb{R}$, then there exists a diffeomorphism $f: Y \rightarrow Y$ with $f(M_1) = M_2$.

Theorem (Meeks-Pérez)

- Suppose that Y is a 3-dimensional metric Lie group, not necessarily simply connected.
- The compact, orientable strongly stable H -surfaces in Y are precisely the left cosets of compact 2-dimensional subgroups of Y and furthermore, all such subgroups are tori which are normal subgroups of Y .
- In particular, the existence of such strongly stable compact H -surfaces in Y implies that the fundamental group of Y contains a subgroup isomorphic to $\mathbb{Z} \times \mathbb{Z}$.

Corollary (Unknottedness Theorem for Minimal Surfaces in $SU(2)$)

Let X be isomorphic to $SU(2)$ and let M_1, M_2 be two compact, diffeomorphic embedded minimal surfaces in X . Then there exists a diffeomorphism $f: X \rightarrow X$ with $f(M_1) = M_2$.

Proof.

- By Waldhausen, it suffices to prove that the closure of each complement of $X - M_i$ is a handlebody.
- Otherwise by Meeks-Simon-Yau, X admits an embedded, compact, strongly stable minimal surface, which contradicts the above theorem. \square

Theorem (Positive Injectivity Radius of Classical Minimal Surfaces, Meeks-Pérez)

- A complete embedded minimal surface M of finite topology in a homogeneous 3-manifold Y has positive injectivity radius.
- More generally, a complete embedded H -surface M of finite topology in a homogeneous 3-manifold Y has positive injectivity radius, when $H < H(Y)$.

Remark

- **Meeks-Tinaglia** proved that a complete embedded H -surface of finite topology in a homogeneously regular 3-manifold of non-positive curvature has bounded second fundamental form when $H > 0$, and hence, it positive injectivity radius.
- Their result in the non-positive sectional curvature setting was motivated by the earlier proof by **Meeks-Rosenberg** that a complete embedded minimal surface of finite topology in a homogeneously regular 3-manifold of non-positive curvature has positive injectivity radius.

Conjecture (Positive Injectivity Radius/Bounded Curvature Conjecture, Meeks-Pérez-Tinaglia)

- A complete embedded H -surface of finite topology in X with $H \geq H(X)$ has positive injectivity radius and bounded curvature.
- A complete embedded H -surface of finite genus surface in X with $H = H(X)$ has positive injectivity radius and bounded curvature.

Remark

Curvature estimates of **Meeks-Tinaglia** for embedded ($H > 0$)-disks imply that any complete embedded ($H > 0$)-surface of positive injectivity radius in a homogeneously regular **3**-manifold has bounded second fundamental form.

Conjecture (Bounded Curvature Conjecture, Meeks-Tinaglia)

- The norm of the second fundamental of any complete embedded finite topology ($H > 0$)-surface in X is bounded.
- More generally, the same result holds for the case for any complete **3**-manifold locally isometric to X .

Conjecture (Calabi-Yau Properness Problem, Meeks-Pérez)

- A complete, connected, embedded H -surface of positive injectivity radius is proper in X whenever $H \geq H(X)$.
- In particular, by a result of Meeks-Pérez, complete, embedded minimal surfaces of finite topology in metric Lie groups isomorphic to \mathbb{R}^3 , Nil_3 , $\tilde{E}(2)$, Sol_3 would always be proper.

Conjecture (Stability Conjecture for $SU(2)$, Meeks-Pérez-Ros)

If X is diffeomorphic to S^3 , then X contains no strongly stable complete H -surfaces.

Meeks-Pérez-Ros

- Conjecture is true if X is a Berger sphere with non-negative scalar curvature.
- Also true if X is $SU(2)$ endowed with a left invariant metric of positive scalar curvature.
- If Y is a 3-sphere with a Riemannian metric (not necessarily a left invariant metric) such that it admits no strongly stable complete minimal surfaces, then for each integer $g \in \mathbb{N} \cup \{0\}$, the space of compact embedded minimal surfaces of genus g in Y is compact.

Conjecture (Calabi-Yau Properness Problem, Meeks-Pérez)

- A complete, connected, embedded H -surface of positive injectivity radius is proper in X whenever $H \geq H(X)$.
- In particular, by a result of Meeks-Pérez, complete, embedded minimal surfaces of finite topology in metric Lie groups isomorphic to \mathbb{R}^3 , Nil_3 , $\tilde{E}(2)$, Sol_3 are proper.